



Engineering a Safer (and More Secure) World

Nancy Leveson
Col. Bill Young
MIT



Safety vs. Security

- Safety: prevent losses due to **unintentional actions** by **benevolent actors**
- Security: prevent losses due to **intentional actions** by **malevolent actors**
- Key difference is intent
- Common goal: loss prevention
 - Ensure that critical functions and services provided by networks and services are maintained
 - An integrated approach to safety and security is possible
 - New paradigm for safety will work for security too

Traditional Approach to Safety

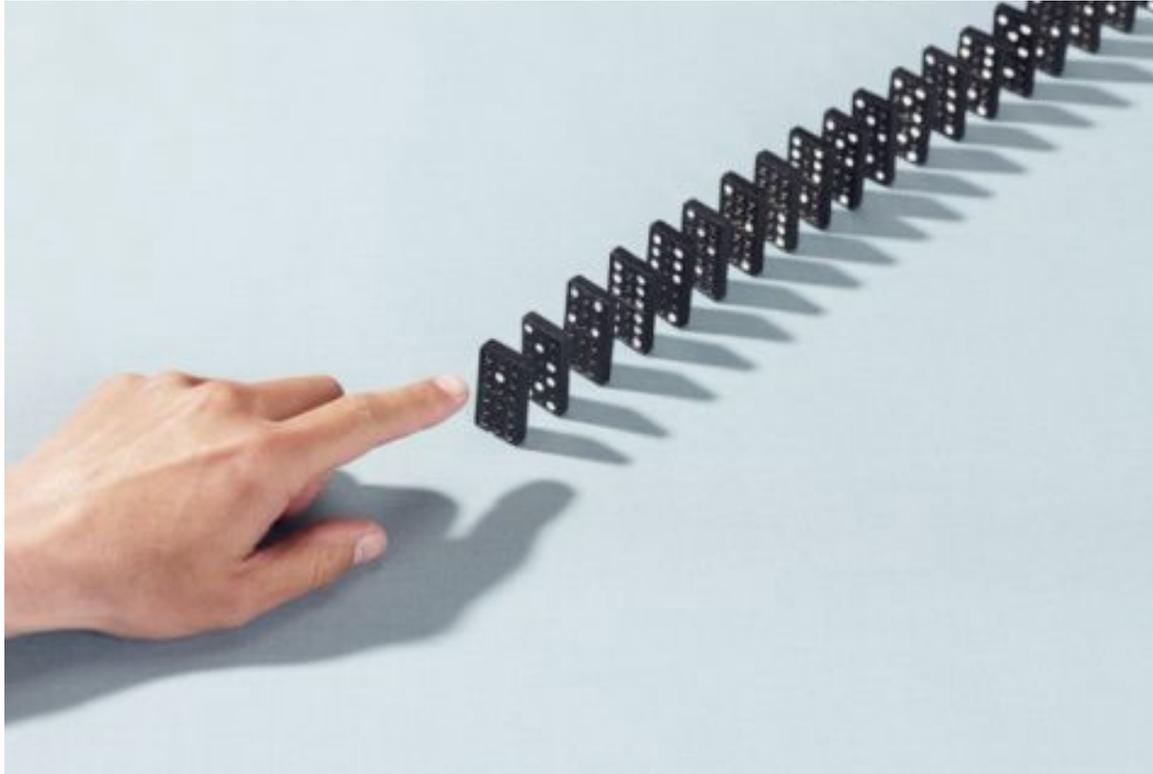
- Traditionally view safety as a failure problem
 - Chain of directly related failure events leads to loss
- Forms the basis for most safety engineering and reliability engineering analysis:

e.g, FTA, PRA, FMECA, Event Trees, etc.

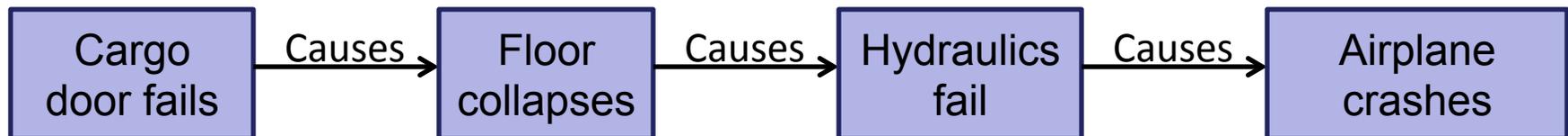
and design (Establish barriers between events or try to prevent individual component failures:

e.g., redundancy, overdesign, safety margins, interlocks, fail-safe design,

Domino “Chain of events” Model

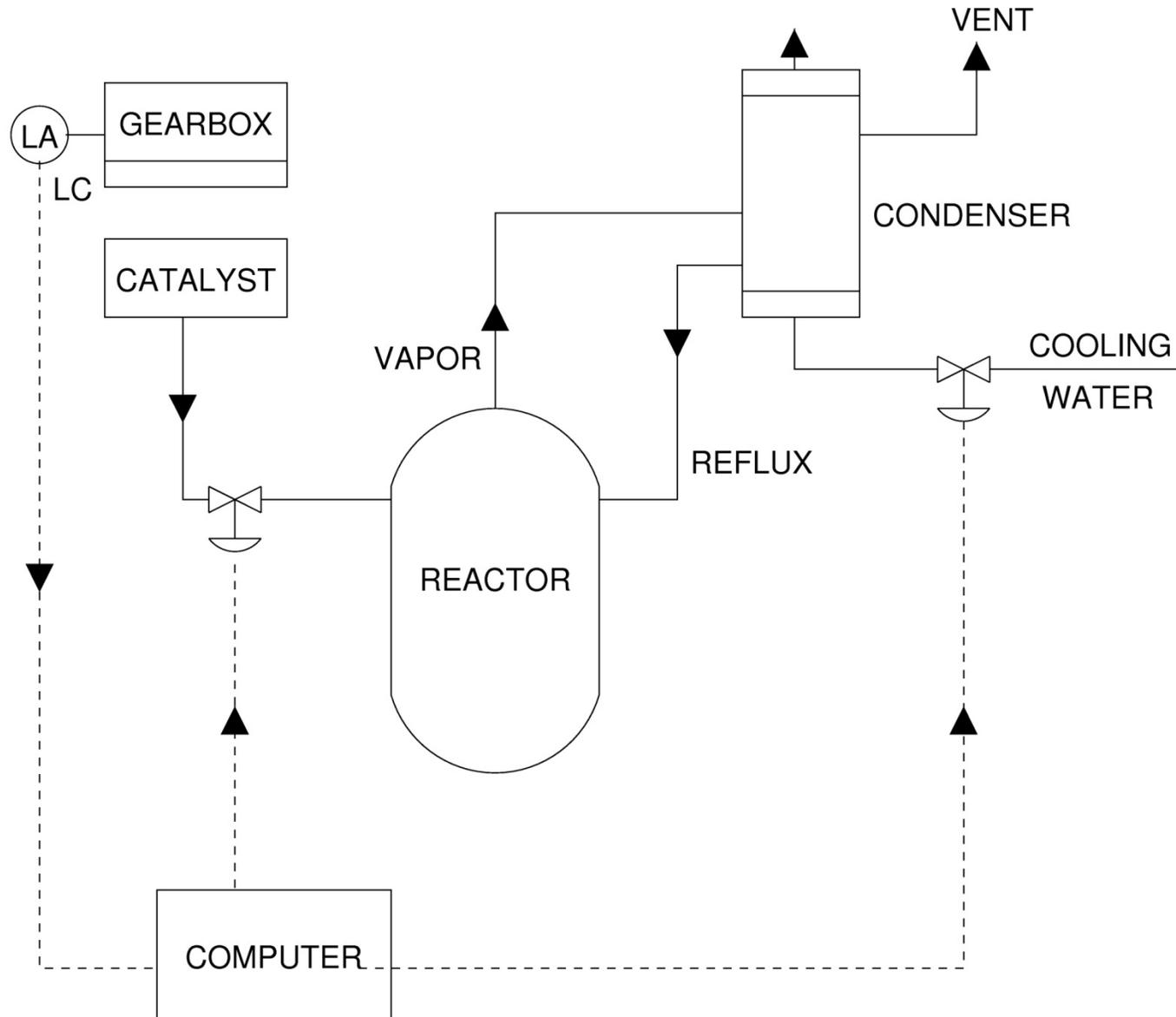


DC-10:



Failure Event-Based

Accident with No Component Failures



Types of Accidents

- Component Failure Accidents
 - Single or multiple component failures
 - Usually assume random failure
- Component Interaction Accidents
 - Arise in interactions among components
 - Related to interactive complexity and tight coupling
 - Exacerbated by introduction of computers and software but problem is system design errors

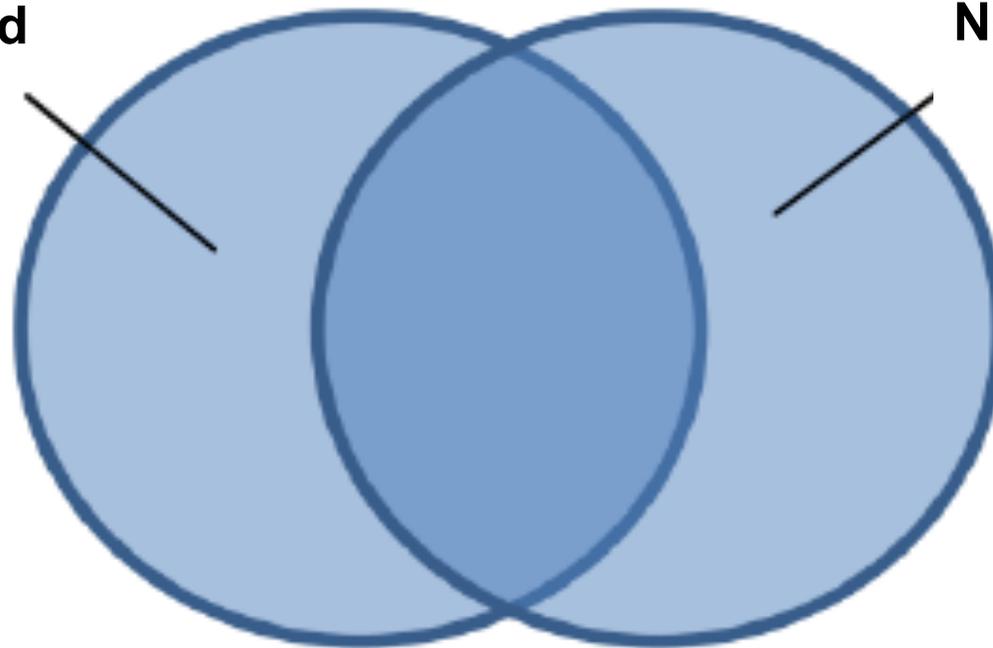
Interactive Complexity

- Arises in interactions among system components
 - Software allows us to build highly coupled and interactively complex systems
 - Coupling causes interdependence
 - Increases number of interfaces and potential interactions
- Too complex to anticipate all potential interactions
- May lead to accidents even when no individual component failures

Confusing Safety and Reliability

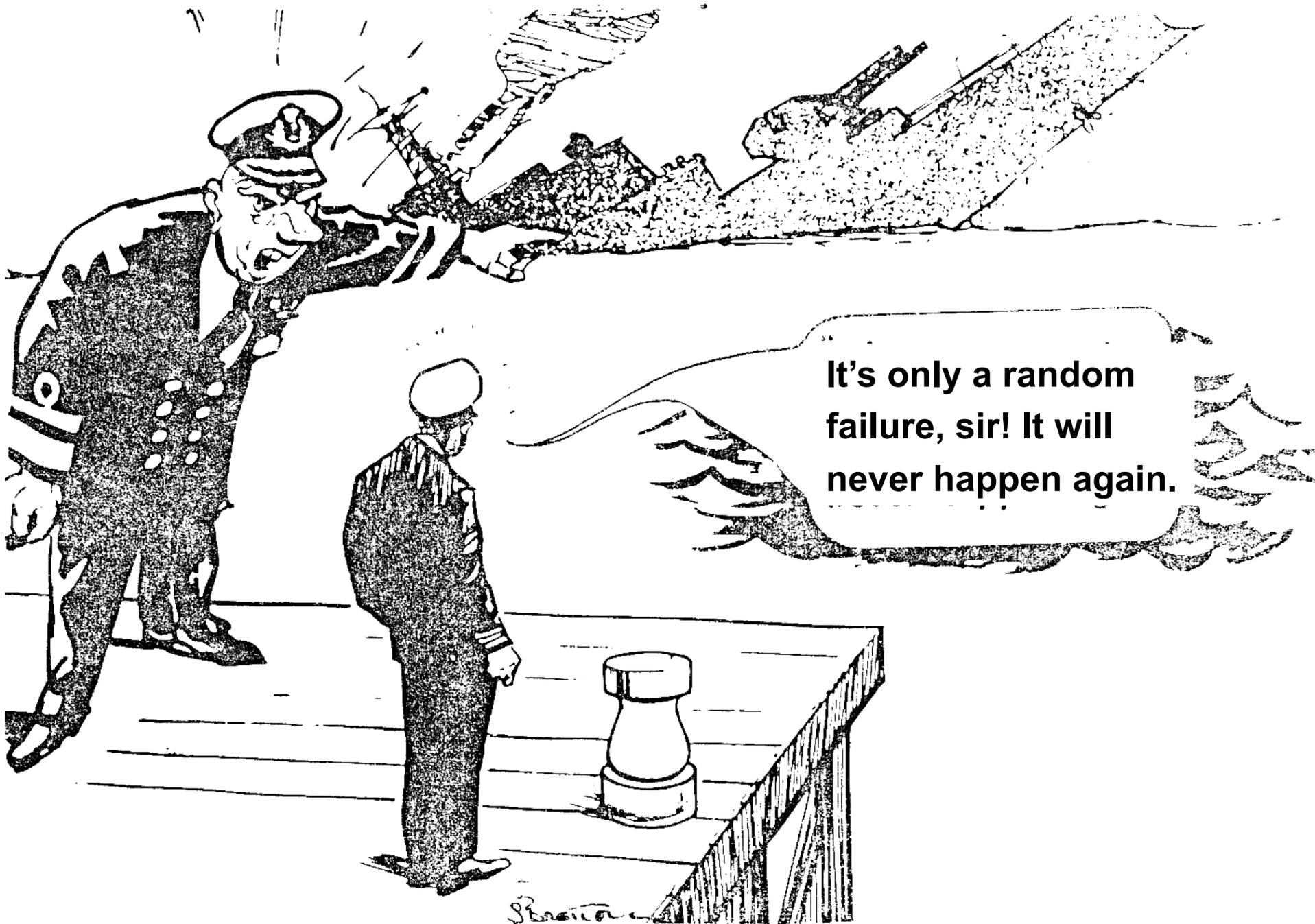
Not safety related

Not reliability related



Scenarios
involving
failures

Unsafe
scenarios



It's only a random failure, sir! It will never happen again.

S. Brown

Safety \neq Reliability

- Safety and reliability are NOT the same
 - Sometimes increasing one can even decrease the other.
 - Making all the components highly reliable will have no impact on component interaction accidents.
- For relatively simple, electro-mechanical systems with primarily component failure accidents, reliability engineering can increase safety.
- But this is untrue for complex, software-intensive socio-technical systems.

Software-Related Accidents

- Are usually caused by flawed requirements
 - Incomplete or wrong assumptions about operation of controlled system or required operation of computer
 - Unhandled controlled-system states and environmental conditions
- Merely trying to get the software “correct” or to make it reliable will not make it safer under these conditions.

Software-Related Accidents (2)

- Software may be highly reliable and “correct” and still be unsafe:
 - Correctly implements requirements but specified behavior unsafe from a system perspective.
 - Requirements do not specify some particular behavior required for system safety (incomplete)
 - Software has unintended (and unsafe) behavior beyond what is specified in requirements.

Limitations of Traditional Approach (1)

- Systems are becoming more complex
 - Accidents often result from interactions among components, not just component failures
 - Too complex to anticipate all potential interactions
 - By designers
 - By operators
 - Indirect and non-linear interactions

Limitations of Traditional Approach (2)

- Omits or oversimplifies important factors
 - Component interaction accidents (vs. component failure accidents)
 - Indirect or non-linear interactions and complexity
 - Systemic factors in accidents
 - Human “errors”
 - System design errors (including software errors)
 - Evolution and change over time



So What Do We Need to Do?

“Engineering a Safer World”

- Expand our accident causation models
- Create new, more powerful and inclusive hazard analysis techniques
- Use new system design techniques
 - Safety-driven design
 - Improved system engineering
- Improve accident analysis and learning from events
- Improve control of safety during operations
- Improve management decision-making and safety culture

Nancy Leveson, *Engineering a Safer World:*
Systems Thinking Applied to Safety



MIT Press, January 2012

STAMP

(System-Theoretic Accident Model and Processes)

- A new, more powerful accident causation model
- Based on systems theory, not reliability theory
- Treats accidents as a dynamic control problem (vs. a failure problem)
- Includes
 - Entire socio-technical system (not just technical part)
 - Component interaction accidents
 - Software and system design errors
 - Human errors

Introduction to Systems Theory

Ways to cope with complexity

1. Analytic Reduction
2. Statistics

Analytic Reduction

- Divide system into distinct parts for analysis
 - Physical aspects → Separate physical components
 - Behavior → Events over time
- Examine parts separately
- Assumes such separation possible:
 1. The division into parts will not distort the phenomenon
 - Each component or subsystem operates independently
 - Analysis results not distorted when consider components separately

Analytic Reduction (2)

2. Components act the same when examined singly as when playing their part in the whole
 - Events not subject to feedback loops and non-linear interactions

3. Principles governing the assembling of components into the whole are themselves straightforward
 - Interactions among subsystems simple enough that can be considered separate from behavior of subsystems themselves
 - Precise nature of interactions is known
 - Interactions can be examined pairwise

Called **Organized Simplicity**

Statistics

- Treat system as a structureless mass with interchangeable parts
- Use Law of Large Numbers to describe behavior in terms of averages
- Assumes components are sufficiently regular and random in their behavior that they can be studied statistically

Called **Unorganized Complexity**

Complex, Software-Intensive Systems

- Too complex for complete analysis
 - Separation into (interacting) subsystems distorts the results
 - The most important properties are emergent
- Too organized for statistics
 - Too much underlying structure that distorts the statistics

Called **Organized Complexity**

Systems Theory

- Developed for biology (von Bertalanffy) and engineering (Norbert Wiener)
- Basis of system engineering and system safety
 - ICBM systems of the 1950s
 - Developed to handle systems with “organized complexity”

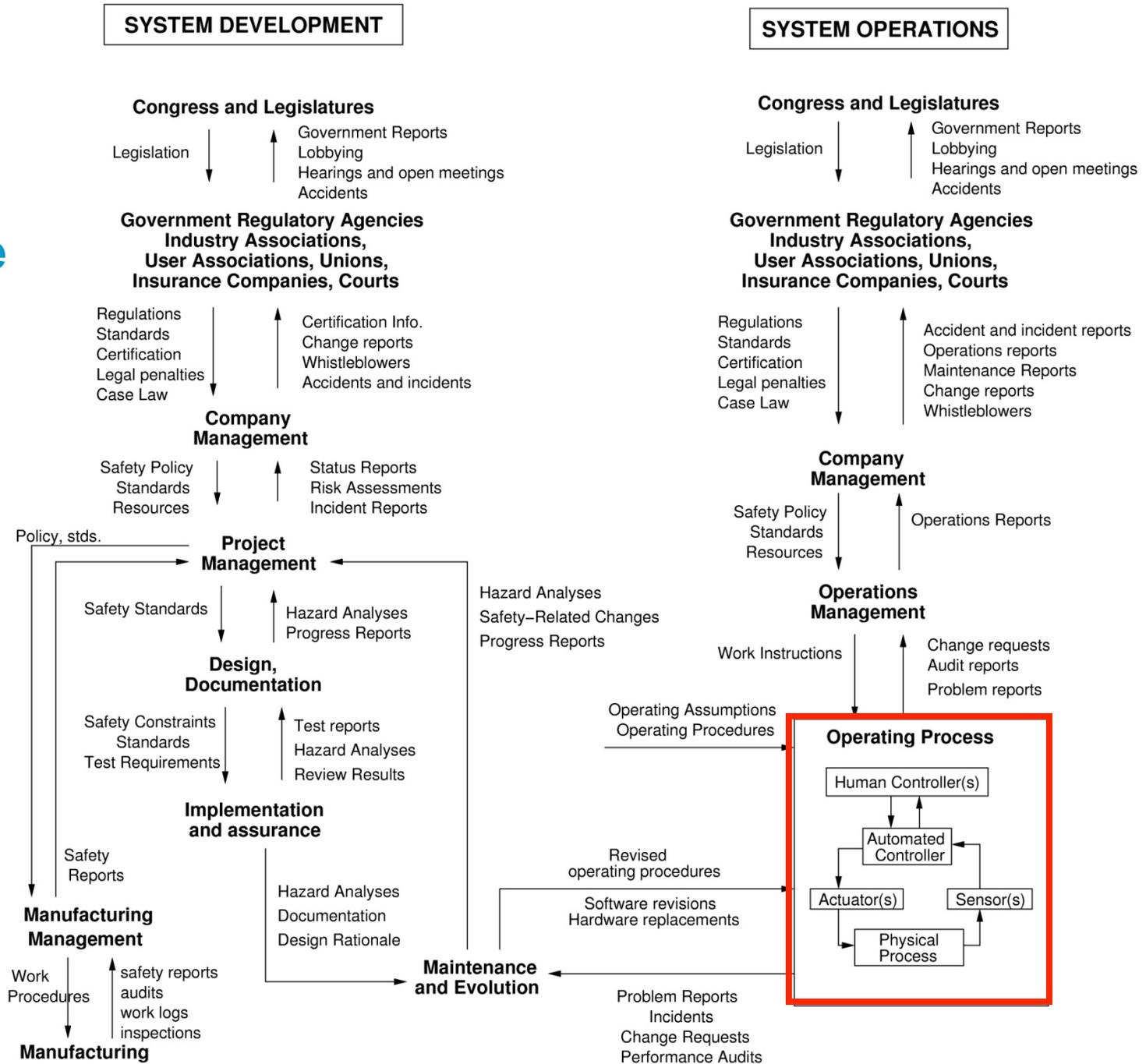
Systems Theory (2)

- Focuses on systems taken as a whole, not on parts taken separately
 - Some properties can only be treated adequately in their entirety, taking into account all social and technical aspects
 - These properties derive from relationships among the parts of the system
 - How they interact and fit together
- Two pairs of ideas
 1. Hierarchy and emergence
 2. Communication and control

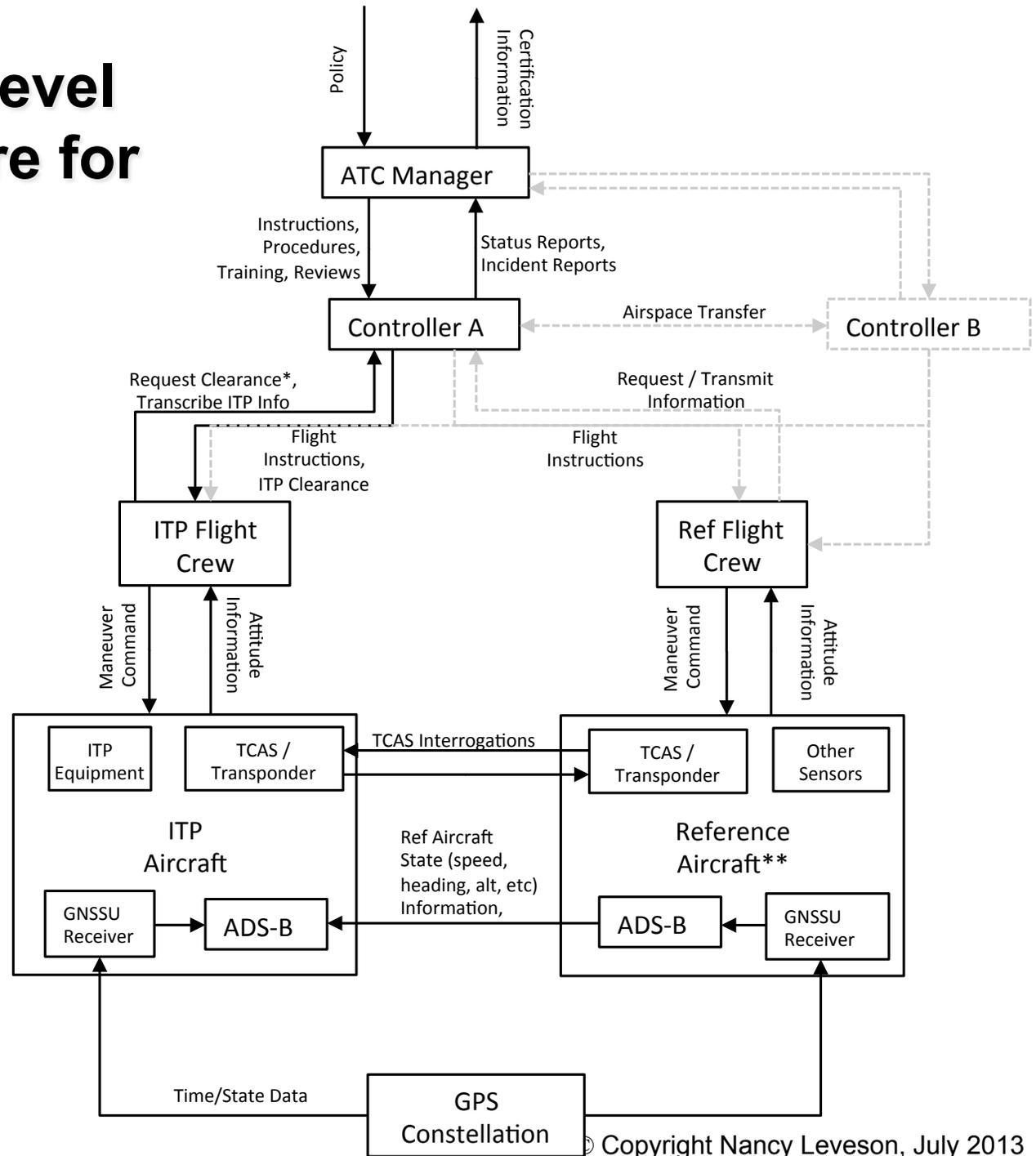
Hierarchy and Emergence

- Complex systems can be modeled as a hierarchy of organizational levels
 - Each level more complex than one below
 - Levels characterized by emergent properties
 - Irreducible
 - Represent constraints on the degree of freedom of components at lower level
- Safety is an emergent system property
 - It is NOT a component property
 - It can only be analyzed in the context of the whole
- Security is another emergent property

Example Safety Control Structure



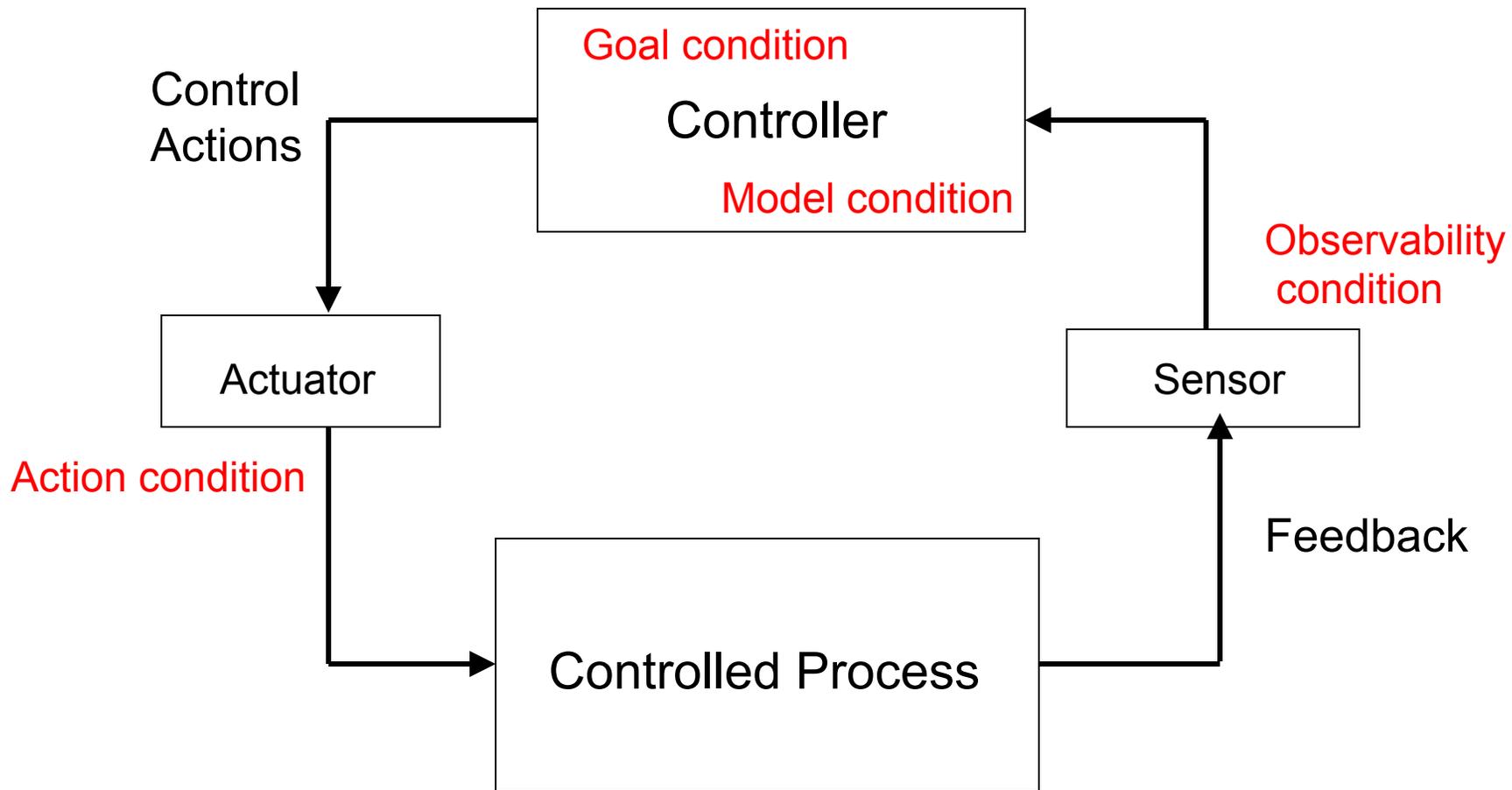
Example High-Level Control Structure for ITP



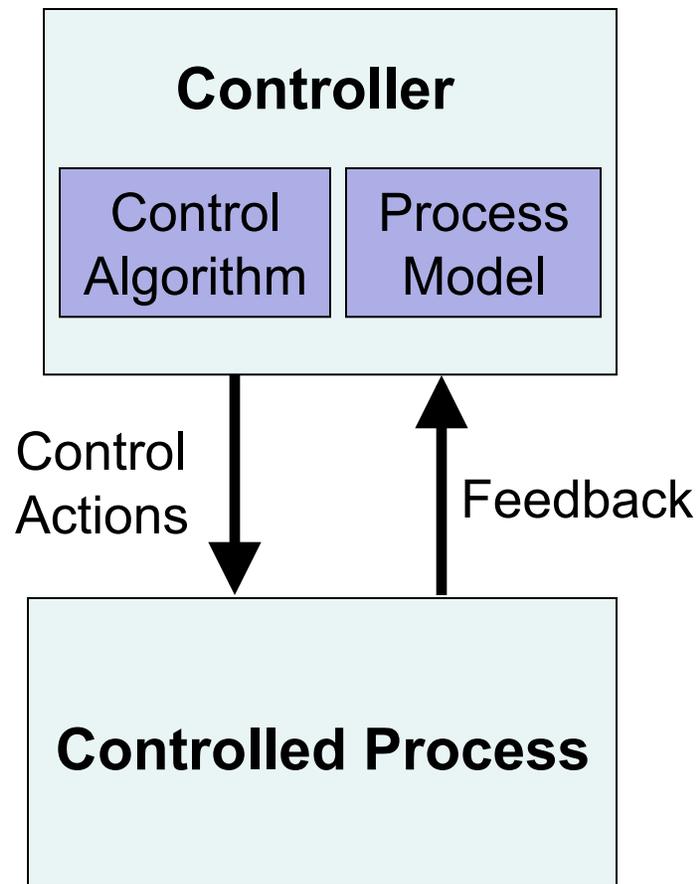
Communication and Control

- Hierarchies characterized by control processes working at the interfaces between levels
- A control action imposes constraints upon the activity at a lower level of the hierarchy
- Systems are viewed as interrelated components kept in a state of dynamic equilibrium by feedback loops of information and control
- Control in open systems implies need for communication

Control processes operate between levels of hierarchy



Role of Process Models in Control



- Controllers use a **process model** to determine control actions
- Accidents often occur when the process model is incorrect
- Four types of hazardous control actions:
 - Control commands required for safety are not given
 - Unsafe ones are given
 - Potentially safe commands given too early, too late
 - Control stops too soon or applied too long

STAMP: Safety as a Control Problem

- Safety is an emergent property that arises when system components interact with each other within a larger environment
 - A set of constraints related to behavior of system components (physical, human, social) enforces that property
 - Accidents occur when interactions violate those constraints (a lack of appropriate constraints on the interactions)
- Goal is to control the behavior of the components and systems as a whole to ensure safety constraints are enforced in the operating system.

STAMP (2)

- Accidents involve a complex, dynamic “process”
 - Not simply chains of failure events
 - Arise in interactions among humans, machines and the environment
- Treat safety as a dynamic control problem rather than a reliability problem

Examples of Safety Constraints

- Power must never be on when access door open
- Two aircraft must not violate minimum separation
- Aircraft must maintain sufficient lift
- Public health system must prevent exposure of public to contaminated water and food products

Safety as a Dynamic Control Problem

- Examples
 - O-ring did not control propellant gas release by sealing gap in field joint of Challenger Space Shuttle
 - Software did not adequately control descent speed of Mars Polar Lander
 - At Texas City, did not control the level of liquids in the ISOM tower
 - In Deepwater Horizon, did not control the pressure in the well
 - Financial system did not adequately control the use of financial instruments

Safety as a Dynamic Control Problem (2)

- Events are the result of the inadequate control
 - Result from lack of enforcement of safety constraints in system design and operations
- Losses (accidents) are the result of complex dynamic processes where the safety constraints are not enforced by the safety control structure
- A change in emphasis:

~~“prevent failures”~~



“enforce safety constraints on system behavior”

Safety as a Control Problem

- Identify the safety constraints
- Design a control structure to enforce constraints on system behavior and adaptation
 - Physical design (inherent safety)
 - Operations
 - Management
 - Social interactions and culture

Processes

System Engineering
(e.g., Specification,
Safety-Guided Design,
Design Principles)

Risk Management

Management Principles/
Organizational Design

Operations

Regulation

Tools

Accident/Event Analysis
CAST

Hazard Analysis
STPA

Specification Tools
SpecTRM

Organizational/Cultural
Risk Analysis

Identifying Leading
Indicators

Security Analysis

STAMP: Theoretical Causality Model

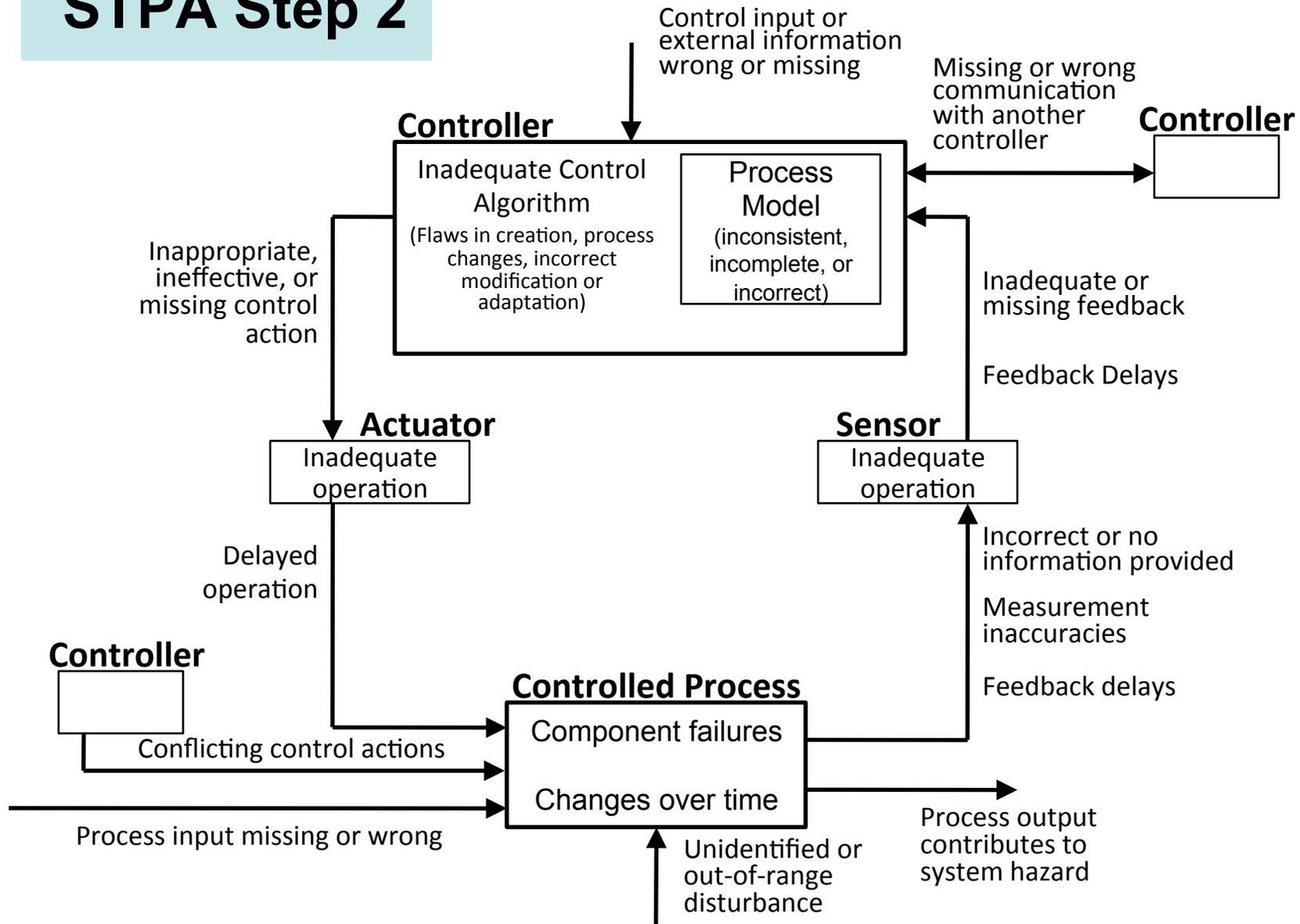
STPA

- Integrated into system engineering
 - Can be used from beginning of project
 - Safety-guided design
- Works on social and organizational aspects of systems
- Generates system and component safety requirements (constraints)
- Identifies flaws in system design and scenarios leading to violation of a safety requirement (i.e., a hazard)

Steps in STPA

- Identify accidents
- Identify hazards
- Construct functional control structure
- Identify unsafe control actions
- Define system and component safety requirements
- Identify causal scenarios for unsafe control actions
- Augment system and component safety requirements

STPA Step 2



Is it Practical?

- STPA has been or is being used in a large variety of industries
 - Spacecraft
 - Aircraft and Integrated Modular Avionics
 - Air Traffic Control
 - UAVs (RPAs)
 - Defense
 - Automobiles
 - Medical Devices
 - Chemical plants
 - Oil and Gas
 - Nuclear and Electrical Power
 - CO₂ Capture, Transport, and Storage
 - Etc.

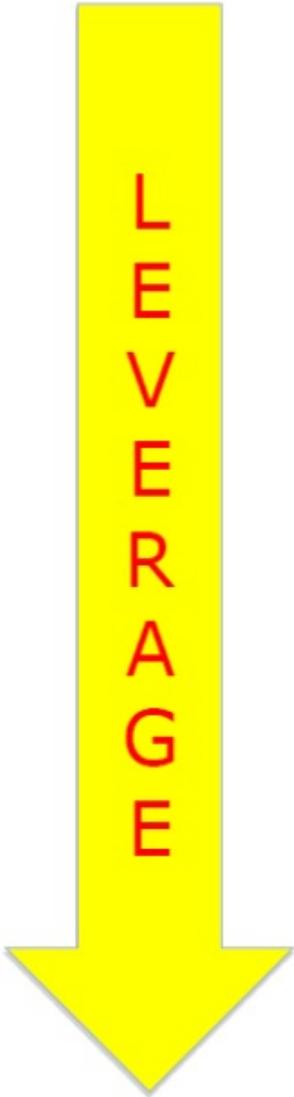
Is it Practical? (2)

Social and Managerial

- Analysis of the management structure of the space shuttle program (post-Columbia)
- Risk management in the development of NASA's new manned space program (Constellation)
- NASA Mission control — re-planning and changing mission control procedures safely
- Food safety
- Safety in pharmaceutical drug development
- Risk analysis of outpatient GI surgery at Beth Israel Deaconess Hospital
- Analysis and prevention of corporate fraud
- UAVs in civilian airspace

Does it Work?

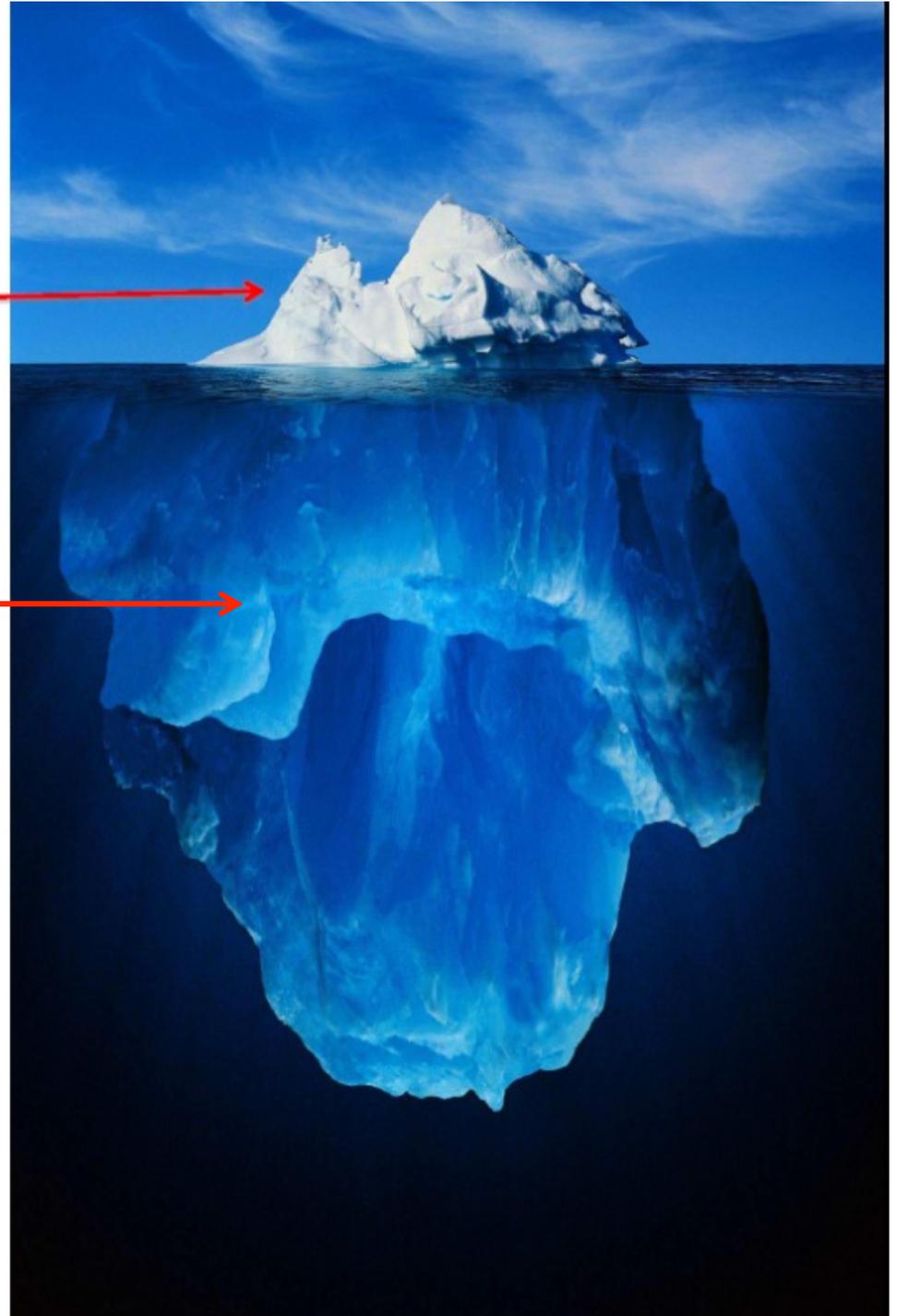
- Most of these systems are very complex (e.g., the U.S. Missile Defense System)
- In all cases where a comparison was made:
 - STPA found the same hazard causes as the old methods
 - Plus it found more causes than traditional methods
 - Sometimes found accidents that had occurred that other methods missed
 - Cost was orders of magnitude less than the traditional hazard analysis methods



Event-based thinking



Systems Thinking



Integrated Approach to Safety and Security

- Both concerned with losses (intentional or unintentional)
- Starts with defining unacceptable losses
 - “What”: essential services to be secured
 - “What” used later to reason thoroughly about “how” best to guard against threats
 - Analysis moves from general to specific
 - Less likely to miss things
 - Easier to review

Strategy vs. Tactics

- Strategy vs. tactics
 - Cyber security often framed as battle between adversaries and defenders (tactics)
 - Requires correctly identifying attackers motives, capabilities, targeting
- Can reframe problem in terms of strategy
 - Identify and control system vulnerabilities (vs. reacting to potential threats)
 - Top-down vs. bottom-up tactics approach
 - Tactics tackled later

Top-Down Approach

- Starts with identifying losses and safety/security constraints
- Build functional control model
 - Controlling constraints whether safety or security
 - Includes physical, social, logical and information, operations, and management aspects
- Identify unsafe/unsecure control actions and causes for them
 - May have to add new causes, but rest of process is the same

Example: Stuxnet

- Loss: damage to reactor (in this case centrifuges)
- Hazard/Vulnerability: Centrifuges are damaged by spinning too fast
- Constraint: Centrifuges must never spin above maximum speed
- Hazardous control action: Issuing *increase speed* command when already spinning at maximum speed
- One potential cause:
 - Incorrect process model: thinks spinning at less than maximum speed
 - Could be inadvertent or advertent

Evaluation

- Informal so far but with real red teams
 - Went through STPA-Sec steps
 - Found things they had not thought of before
- Formal experiment in Spring 2014

Summary

- Key question: How to control vulnerabilities, not how to avoid threats
- Starts with system vulnerabilities and moves down to identify threats (top-down systems engineering approach)

vs.

Starting with threats and moving up to vulnerabilities they might exploit to produce a loss (bottom-up approach)

- Elevates security problem from guarding network to higher-level problem of assuring overall function of enterprise.